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Filipovic, Jiri Masaryk Univ.
Peterlik, Igor Masaryk Univ.
Matyska, Ludek Masaryk Univ.

Poster 4 PhyNeSS: A Physics-Driven Neural Networks-Based Surgery Simulation System with Force Feedback, pp. 30-34.
Deo, Dhanannjay Rensselaer Pol. Inst.
De, Suvranu Rensselaer Pol. Inst.

Poster 7 Data-Driven Haptic Modeling Using Polynomial Hypersurfaces, pp. 35-38.
Theodosis, Paul Brigham Young Univ.
Colton, Mark Brigham Young Univ.

Poster 10 Computationally Efficient Techniques for Data-Driven Haptic Rendering, pp. 39-44.
Hoever, Raphael ETH Zurich
Di Luca, Massimiliano Max Planck Inst. for Biological Cybernetics
Szekely, Gabor ETH Zurich
Harders, Matthias ETH Zurich

Collaboration and Control

Poster 13 Homotopy Switching Model for Dyad Haptic Interaction in Physical Collaborative Tasks, pp. 45-50.
Evrard, Paul CNRS/AIST
Kheddar, Abderrahmane JRL CNRS

Poster 16 Role Determination in Human-Human Interaction, pp. 51-56.
Stefanov, Nikolay Tech. Univ. München
Peer, Angelika Tech. Univ. München
Buss, Martin Tech. Univ. München

Poster 19 Maneuverability of Master Control Devices Considering the Musculo-Skeletal Model of an Operator, pp. 57-62.
Ito, Sho Kyoto Univ.
Yokokohji, Yasuyoshi Kyoto Univ.

Poster 22 Control Strategies and Perception Effects in Co-Located and Large Workspace Dynamical Encountered Haptics, pp. 63-68.
Tripicchio, Paolo Scuola Superiore S.Anna
Tactile Displays 2

Kim, Seung-Chan KAIST
Yang, Tae-Heon KAIST
Han, Byung-Kil KAIST
Kim, Chong Hui Agency for Defense Development
Yang, Gi-Hun KIST
Kang, Sungchul KIST
Kwon, Dong-Soo KAIST

Poster 28 Determining Appropriate Parameters to Elicit Linear and Circular Apparent Motion Using Vibrotactile Cues, pp. 75-78.
Niwa, Masataka Osaka Univ.
Ito, Yuichi Osaka Univ.
Kishino, Fumio Osaka Univ.

Poster 31 Vibrotactile Display for Hand-Held Input Device Providing Spatial and Directional Information, pp. 79-84.
Yang, Gi-Hun KIST
Ryu, Dongseok KIST
Kang, Sungchul KIST

M’Boungui, Gaston IRCICA
Lemaire-Semail, Betty IRCICA
Giraud, Frederic IRCICA

Haptic Device Design 1

Poster 37 Compact MR-Brake with Serpentine Flux Path for Haptics Applications, pp. 91-96.
Senkal, Doruk Washington State Univ. Vancouver
Gurocak, Hakan Washington State Univ. Vancouver

Tsetserukou, Dzmitry The Univ. of Tokyo
Tachi, Susumu The Univ. of Tokyo
Schiele, Andre European Space Agency

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Lee, In POSTECH
Hwang, Inwook POSTECH
Han, Kyung Lyong POSTECH
Choi, Oh Kyu POSTECH
Choi, Seungmoon POSTECH
Lee, Jin S. POSTECH

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Salisbury, Curt Stanford Univ.
Gillespie, Brent Univ. of Michigan
Tan, Hong Purdue Univ.
Barbagli, Federico Stanford Univ.
Salisbury, Kenneth Stanford Univ.

Poster 52 Stiffness Discrimination with Visual and Proprioceptive Cues, pp. 121-126.
Gurari, Netta Johns Hopkins Univ.
Kuchenbecker, Katherine J. Univ. of Pennsylvania
Okamura, Allison M. Johns Hopkins Univ.

Furukawa, Masahiro The Univ. of Electro-Communications
Nagaya, Naohisa The Univ. of Electro-Communications
Hashimoto, Yuki The Univ. of Electro-Communications
Kajimoto, Hiroyuki The Univ. of Electro-Communications
Inami, Masahiko Keio Univ.

Poster 58 Signal Manipulation Based on Perceptual Thresholds Enhances Surface Experience with Common Haptic Device, pp. 133-138.
Vicentini, Marco Univ. of Verona
Botturi, Debora Univ. of Verona

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Kuroki, Shinobu The Univ. of Tokyo
Watanabe, Junji NTT Communication
Kawakami, Naoki The Univ. of Tokyo
Tachi, Susumu The Univ. of Tokyo

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Shih, Ron Univ. of Waterloo
Dubrowski, Adam Univ. of Toronto
Carnahan, Heather Univ. of Toronto

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Suzuki, Yuika Tohoku Univ.
Gyoba, Jiro Tohoku Univ.

Poster 67 The Impact of Feedback Design in Haptic Volume Visualization, pp. 154-159.
Lundin Palmerius, Karljohan Linköping Univ.
Forsell, Camilla Linköping Univ.

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Menelas, Bob CNRS-LIMSI
Ammi, Mehdi Univ. of Paris-XI
Pastur, Luc CNRS-LIMSI
Bourdot, Patrick CNRS-LIMSI

Ohara, Eiichi Gifu Univ.
Yano, Ken'ichi Gifu Univ.
Horihata, Satoshi Nihon Univ.
Aoki, Takaaki Gifu Univ.
Nishimoto, Yutaka Gifu Univ.

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Handa, Takuya NHK (Japan Broadcasting Corp.)
Sakai, Tadahiro NHK (Japan Broadcasting Corp.)
Morita, Toshiya NHK (Japan Broadcasting Corp.)

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Cheng, Mario The Univ. of Queensland
Riek, Stephan The Univ. of Queensland
Ourselin, Sebastien Univ. Coll. London
Watson, Marcus Royal Brisbane and Women's Hospital
Passenger, Josh Royal Brisbane and Women's Hospital
Device Design and Applications (Poster with demos)  
(Demo room)

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Hoshi, Takayuki Univ. of Tokyo  
Iwamoto, Takayuki Canon  
Shinoda, Hiroyuki Univ. of Tokyo

Poster B  A High Fidelity Ungrounded Torque Feedback Device: The Itorqu 2.0, pp. 261-266.  
Winfree, Kyle N. Univ. of Pennsylvania  
Gewirtz, Jamie Univ. of Pennsylvania  
Mather, Thomas Univ. of Pennsylvania  
Fiene, Jonathan Univ. of Pennsylvania  
Kuchenbecker, Katherine J. Univ. of Pennsylvania

Visell, Yon McGill Univ.  
Law, Alvin McGill Univ.  
Cooperstock, Jeremy R. McGill Univ.

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Millet, Guillaume Univ. Pierre et Marie Curie-Paris 6  
Haliyo, Dogan Sinan Univ. Pierre et Marie Curie-Paris 6  
Régnier, Stéphane Univ. Pierre et Marie Curie-Paris 6  
Hayward, Vincent Univ. Pierre et Marie Curie-Paris 6

Poster E  Toward Tactilely Transparent Gloves: Collocated Slip Sensing and Vibrotactile Actuation, pp. 279-284.  
Romano, Joseph M. Univ. of Pennsylvania  
Gray, Steven R. Univ. of Pennsylvania  
Jacobs, Nathan T. Univ. of Pennsylvania  
Kuchenbecker, Katherine J. Univ. of Pennsylvania

Tactile Displays 3

Tappeiner, Hanns Carnegie Mellon Univ.  
Klatzky, Roberta Carnegie Mellon Univ.  
Unger, Bertram Carnegie Mellon Univ.
Hollis, Ralph Carnegie Mellon Univ.

Matysek, Marc Tech. Univ. Darmstadt
Lotz, Peter Tech. Univ. Darmstadt
Winterstein, Thomas Tech. Univ. Darmstadt
Schlaak, Helmut F. Tech. Univ. Darmstadt

Kraft, Dirk Univ. of Southern Denmark
Bierbaum, Alexander Univ. of Karlsruhe (TH)
Kjaergaard, Morten Univ. of Southern Denmark
Ratkevicius, Jurgis Univ. of Southern Denmark
Kjær-Nielsen, Anders Univ. of Southern Denmark
Ryberg, Charlotte Univ. of Southern Denmark
Petersen, Henrik Gordon Univ. of Southern Denmark
Asfour, Tamim Univ. of Karlsruhe (TH)
Dillmann, Rüdiger Univ. of Karlsruhe (TH)
Krüger, Norbert Univ. of Southern Denmark

Lee, Jaebong POSTECH
Ryu, Jonghyun POSTECH
Choi, Seungmoon POSTECH

**Dynamics and Control 1**

Shahdi, Ali McMaster Univ.
Sirouspour, Shahin McMaster Univ.

Strolz, Michael Tech. Univ. München
Mörtl, Alexander Tech. Univ. München
Graef, Michael BMW Forschung und Tech. GmbH
Buss, Martin Tech. Univ. München

Kim, Jaeha Gwangju Inst. of Science and Tech.
Kim, Jong-Phil Korea Inst. of Science and Tech.
Seo, Changhoon Gwangju Inst. of Science and Tech.
Ryu, Jeha Gwangju Inst. of Science and Tech.
Poster 35 Recovering Haptic Performance by Relaxing Passivity Requirements, pp. 326-331.
Griffiths, Paul Johns Hopkins Univ.
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Poster 38 Progressive Shared Control for Training in Virtual Environments, pp. 332-337.
Li, Yanfang Rice Univ.
Huegel, Joel C. Rice Univ.
Patoglu, Volkan Sabanci Univ.
O'Malley, Marcia Rice Univ.

Feth, Daniela Tech. Univ. München
Groten, Raphaela Tech. Univ. München
Peer, Angelika Tech. Univ. München
Hirche, Sandra Tech. Univ. München
Buss, Martin Tech. Univ. München

Poster 44 Effects of Magnitude and Phase Cues on Human Motor Adaptation, pp. 344-349.
Israr, Ali Rice Univ.
Kapson, Hakan Sabanci Univ.
Patoglu, Volkan Sabanci Univ.
O'Malley, Marcia Rice Univ.

Ruffaldi, Emanuele Scuola Superiore S. Anna
Filippeschi, Alessandro Scuola Superiore S. Anna
Sandoval, Oscar Scuola Superiore S. Anna
Frisoli, Antonio Scuola Superiore S. Anna
Avizzano, Carlo Alberto Scuola Superiore S. Anna
Bergamasco, Massimo Scuola Superiore S. Anna

Human Performance 2

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Lee, Jin Johns Hopkins Univ.
Okamura, Allison M. Johns Hopkins Univ.
Landau, Barbara Johns Hopkins Univ.
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Kocherry, John SUNY, Univ. at Buffalo  
Srimathveeravalli, Govindarajan SUNY, Univ. at Buffalo  
Chowriappa, Ashirwad SUNY, Univ. at Buffalo  
Kesavadas, Thenkurussi SUNY, Univ. at Buffalo  
Shin, Gwanseob SUNY, Univ. at Buffalo

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Méary, David San Raffaele Vita-Salute Univ.  
Baud-bovy, Gabriel San Raffaele Vita-Salute Univ.

Poster 59 An HMM Approach to Realistic Haptic Human-Robot Interaction,  
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Wang, Zheng Tech. Univ. München  
Peer, AngelikaTech. Univ. München  
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Fujishiro, Issei Tohoku Univ.  
Suzuki, Yasuko Tohoku Univ.  
Takeshima, Yuriko Tohoku Univ.

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Bivall Persson, Petter Linköping Univ.  
Höst, Gunnar E. Linköping Univ.  
Cooper, Matthew David Linköping Univ.  
Tibell, Lena Anna Elisabet Linköping Univ.  
Ynnerman, Anders Linköping Univ.

Poster 9 Dynamic Coupling Haptic Suturing Based on Orthogonal Decomposition,  
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Sepulveda-Cervantes, Gabriel CIDETEC-IPN  
Parra Vega, Vicente Cinvestav  
Dominguez-Ramirez, Omar Arturo Hidalgo State Univ.

Poster 12 Bilateral Energy Transfer for High Fidelity Haptic Telemanipulation,
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Vo, Dao Iowa State Univ.
Vance, Judy Iowa State Univ.
Marasinghe, Mervyn Iowa State Univ.

Poster 18 Multidimensional Visual Aid Enhances Haptic Training Simulations, pp. 500-504.
Halabi, Osama Iwate Univ.
Chiba, Norishige Iwate Univ.

Poster 21 Perceptually Augmented Simulator Design through Decomposition, pp. 505-510.
Edmunds, Timothy Rutgers Univ.
Pai, Dinesh K. Univ. of British Columbia

Poster 24 Performance Improvement with Haptic Assistance: A Quantitative Assessment, pp. 511-516.
Datta, Amitava Univ. of Western Australia

Haptic Device Design 3

Poster 27 Extending the Motion Ranges of Magnetic Levitation for Haptic Interaction, pp. 517-522.
Berkelman, Peter Univ. of Hawaii-Manoa
Dzadovskyy, Michael Univ. of Hawaii-Manoa

Poster 30 Design and Modeling of a Novel Haptic Device, pp. 523-528.
Tang, Zhourning Simon Fraser Univ.
Payandeh, Shahram Simon Fraser Univ.

Poster 33 Variable Resistance Hand Device Using an Electro-Rheological Fluid Damper, pp. 529-534.
Weinberg, Brian Northeastern Univ.
Khanicheh, Azadeh Northeastern Univ.
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Li, Siqiao Scuola Superiore S. Anna
Frisoli, Antonio Scuola Superiore S. Anna
Borelli, Luigi Federico Scuola Superiore S. Anna
Bergamasco, Massimo Scuola Superiore S. Anna
Raabe, Markus Univ. of Regensburg
Greenlee, Mark W. Univ. of Regensburg

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Lee, Dongjun Univ. of Tennessee-Knoxville
Huang, Ke Univ. of Tennessee-Knoxville

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Niakosari, Sina McMaster Univ.
Sirouspour, Shahin McMaster Univ.

Poster 45 Remote Dynamic Proxies for Wave-Based Peer-To-Peer Haptic Interaction, pp. 553-558.
Li, Zhi Univ. of Victoria
Constantinescu, Daniela Univ. of Victoria

Poster 48 Performance of Equivalent Frequency-Dependent Damping, pp. 559-564.
Lim, Yo-An Gwangju Inst. of Science and Tech.
Ahn, Hyo-Sung Gwangju Inst. of Science and Tech.
Ryu, Jeha Gwangju Inst. of Science and Tech.

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Poster 51 Finger Force of Exploratory Movements Is Adapted to the Compliance of Deformable Objects, pp. 565-569.
Kaim, Lukas Univ. of Giessen
Drewing, Knut Univ. of Giessen
Misra, Sarthak The Johns Hopkins Univ.
Fuemnsthahl, Philipp ETH Zurich
Ramesh, K. T. The Johns Hopkins Univ.
Okamura, Allison M. The Johns Hopkins Univ.
Harders, Matthias ETH Zurich

Bocca, Francesca San Raffaele Vita-Salute Univ.
Baud-bovy, Gabriel San Raffaele Vita-Salute Univ.

Poster 60 The Equivalence of Vision and Haptics When Matched Spatiotemporally, pp. 582-586.
Symmons, Mark Monash Univ.
Richardson, Barry Monash Univ.

Tactile Modeling

Galie, Jessica MIT
Ho, Hsin-Ni NTT
Jones, Lynette MIT

Poster 64 Providing Two-Dimensional Tactile Directional Information with One-Dimensional Movement, pp. 593-598.
Lylykangas, Jani Kristian Univ. of Tampere
Surakka, Veikko Univ. of Tampere
Rantala, Jussi Univ. of Tampere
Raisamo, Roope Univ. of Tampere

Borst, Christoph Univ. of Louisiana at Lafayette
Baiyya, Vijay Univ. of Louisiana at Lafayette

Poster 68 Virtual Active Touch: Perceived Roughness through a Pointing-Stick-Type Tactile Interface, pp. 605-610.
Yamauchi, Takahiro Tohoku Univ.
Konyo, Masashi Tohoku Univ.
Okamoto, Shogo Tohoku Univ.
Tadokoro, Satoshi Tohoku Univ.